

PELAJARAN HARI INI

1. Fisika Dasar dan Satuan yang berkaitan dengan Sistem Pneumatik
2. Urutan Perangkat Penyuplai Angin
3. Cara Kerja Katup Sistem Pneumatik

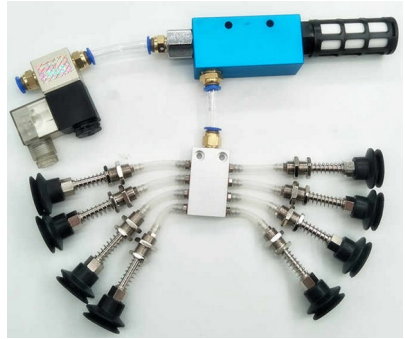
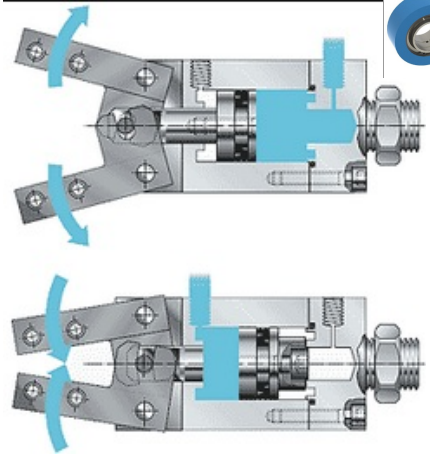
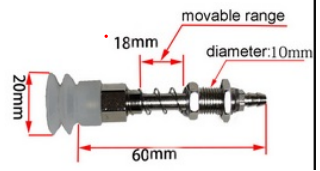
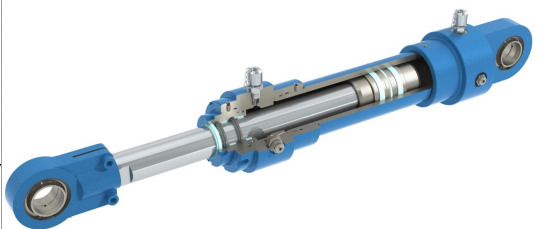
APA YANG DIKENDALIKAN DI SISTEM PNEUMATIC?

Actuators can be further broken down into groups:

- Linear actuators
 - Single-acting cylinder
 - Double-acting cylinder
- Rotary actuators
 - Air motors
 - Rotary actuators



Fig. 2.13 Actuators, linear and rotary



UNTUK APA AKTUATORNYA?

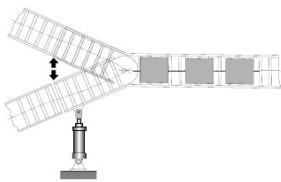


Fig. 1.2
Points switch for two conveyor belts

Fig. 1.3
Pneumatic cutter



Pneumatic



Fig. 1.2:
Processing station

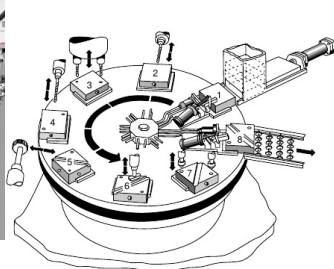


Fig. 2.2:
Positional sketch of the lifting device

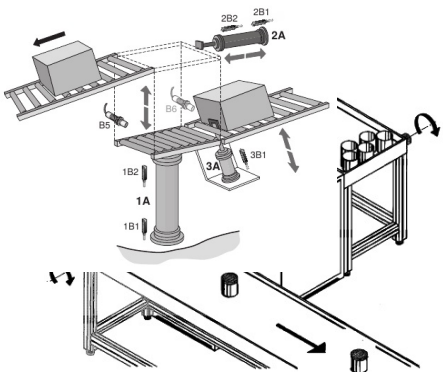


Fig. 1.3:
Assembly device for mounting lids on cans

Electropneumatic

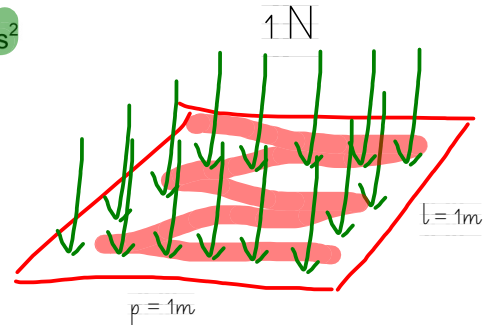
Mengenal Angin Bertekanan

Basic units	Quantity	Symbol	Units
Panjang	Length	L	Meter (m)
Berat	Mass	m	Kilogram (kg)
Waktu	Time	t	Second (s)
Suhu	Temperature	T	Kelvin (K, 0 °C = 273.15 K)

Hukum 2 Newton

$$F = m a$$

Derived units	Quantity	Symbol	Units
Gaya	Force	F	Newton (N) = 1 kg • m/s ²
Luas	Area	A	Square metre (m ²)
Volume	Volume	V	Cubic metre (m ³)
Debit	Flowrate	q _v	(m ³ /s)
Tekanan	Pressure	p	Pascal (Pa) 1 Pa = 1 N/m ² 1 bar = 10 ⁵ Pa m/(s ²)



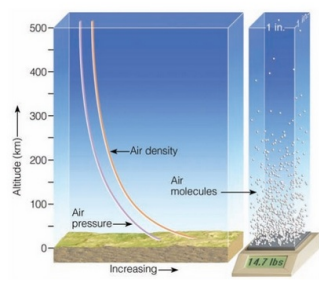
Rumus Percepatan:

$$a = \frac{v_1 - v_0}{t}$$

Keterangan:
 a = percepatan (m/s²)
 v₀ = kecepatan mula-mula (m/s)
 v₁ = kecepatan akhir (m/s)
 t = waktu (s)

Keterangan (V) = rata-rata kecepatan

s = jarak (km)
 t = waktu (jam)
 v = kecepatan (km/jam)

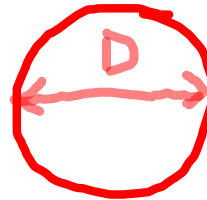
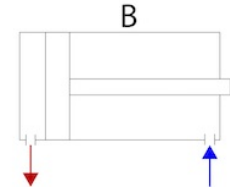
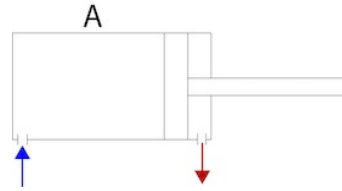
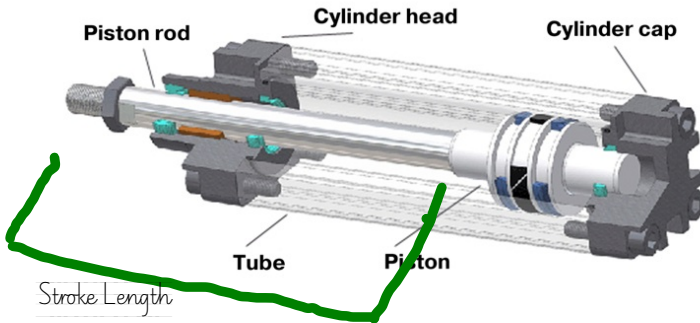


<https://www.youtube.com/watch?v=28qrZdfexT8>

Menentukan Silinder

<https://tameson.com/pages/pneumatic-cylinder-force-calculator>

Components of a piston rod cylinder:



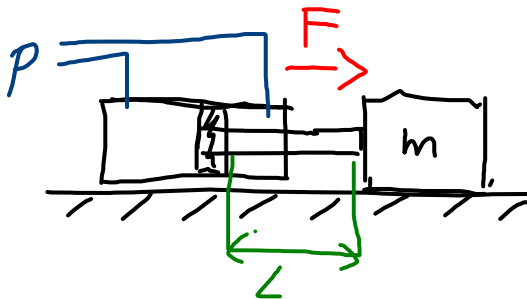
Piston Tampak Belakan (Forward)

$$A = \frac{\pi}{4} \times D^2$$



Piston Tampak Depan (Retract)

$$A = \pi \times \frac{(D^2 - d^2)}{4}$$



$$F = m \cdot a$$

$$= m \cdot \frac{v_2 - v_1}{t}$$

$$= m \cdot \frac{(L/t)}{t}$$

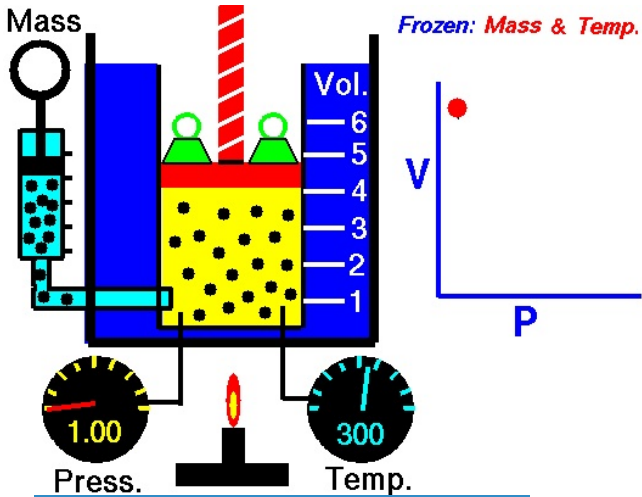
$$F = m \cdot \frac{L}{t^2}$$

$$P = \frac{F}{A}$$

$$\frac{\pi}{4} \times D^2 = \frac{F}{P}$$

$$D = \sqrt{\frac{F \cdot 4}{P \cdot \pi}}$$

Karakteristik Angin

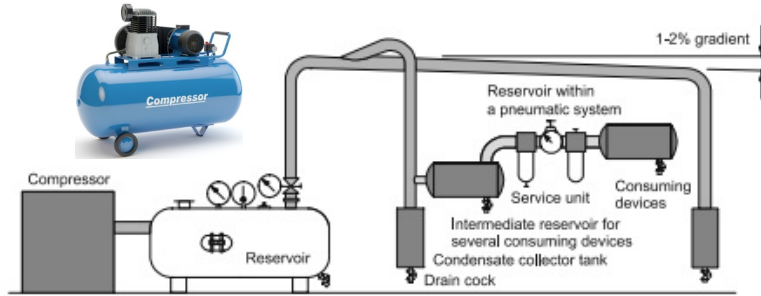


le

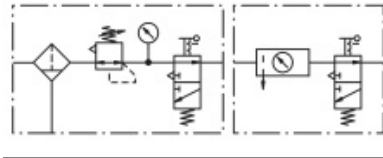
https://upload.wikimedia.org/wikipedia/commons/1/15/Boyles_Law_animated.gif



SUPLAY ELEMENT



Service unit with on-off valve



Manifold

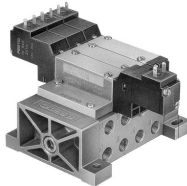
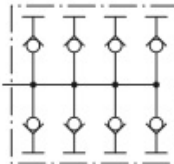


Fig. 4.12. Assembly of electrically actuated directional control valve in a valve manifold block (pneum.)



Pneumatic

Electropneumatic

BAGIAN BAGIAN DARI PNEUMATIC

Fig. 5.2
Positional switch of the stop device

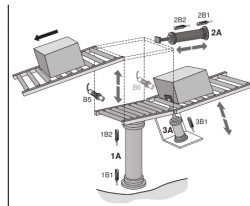
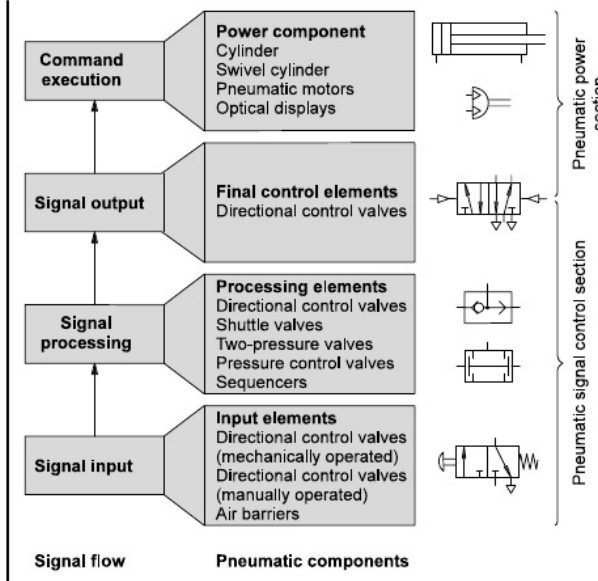
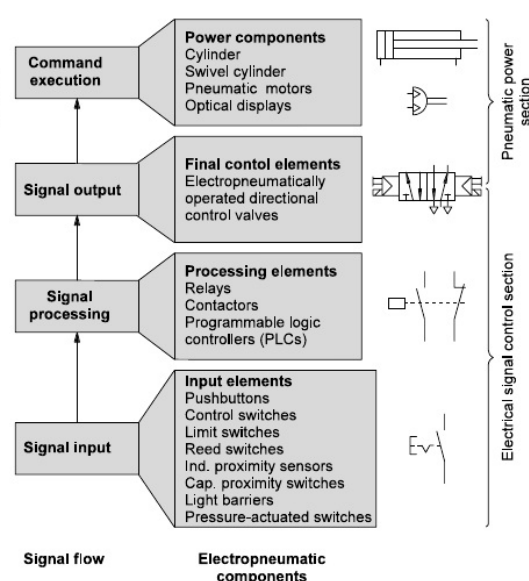


Fig. 1.7:
Signal flow and components of a pneumatic control system



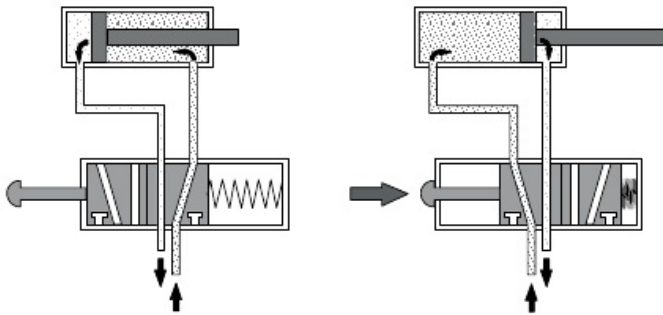
Pneumatic

Fig. 1.8:
Signal flow and components of an electropneumatic control system



Electropneumatic

BAGAIMANA MENGENDALIKAN AKTUATORNYA?



Pneumatic

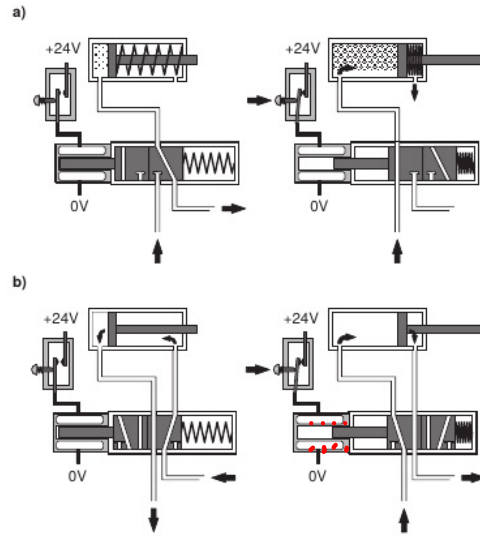
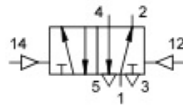
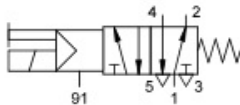
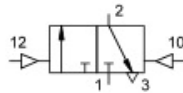
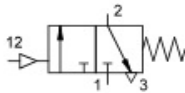


Fig. 4.1: Actuation of a pneumatic cylinder a) Single-acting b) Double-acting



Electropneumatic

MENGENAL VALVE 1



Valve switching positions are represented as squares



The number of squares shows how many switching positions the valve has



Lines indicate flow paths, arrows shows the direction of flow



Shut off positions are identified in the boxes by lines drawn at right angles



The connections (inlet and outlet ports) are shown by lines on the outside of the box

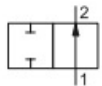


Working lines	ISO 5599-3	Lettering System	Port or Connection
	1	P	Pressure port
	2, 4	A, B	Working lines
	3, 5	R, S	Exhaust ports

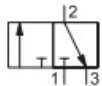
Pilot lines			
	10	Z	Applied signal inhibits flow from port 1 to port 2
	12	Y, Z	Applied signal connects port 1 to port 2
	14	Z	Applied signal connects port 1 to port 4
	81, 91	Pz	Auxiliary pilot air

Number of ports
Number of positions

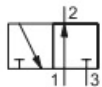
2/2 – Way directional control valve, normally open



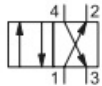
3/2 – Way directional control valve, normally closed



3/2 – Way directional control valve, normally open



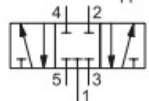
4/2 – Way directional control valve
Flow from 1 → 2 and from 4 → 3



5/2 – Way directional control valve
Flow from 1 → 2 and von 4 → 5

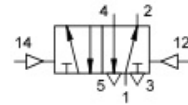
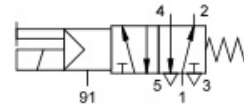
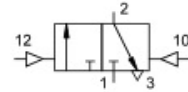
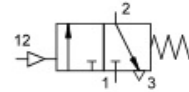


5/3 – Way directional control valve
Mid position closed



MENGENAL VALVE 2

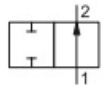
Manual	General	
	Pushbutton	
	Lever Operated	
	Detend lever operated	
	Foot pedal	
Mechanical	Plunger	
	Roller operated	
	Idle return, roller	
	Spring return	
	Spring centred	
Pneumatic	Direct pneumatic actuation	
	Indirect pneumatic actuation (piloted)	
Electrical	Single solenoid operation	
	Double solenoid operation	
Combined	Double solenoid and pilot operation with manual override	



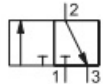
Number of ports

 Number of positions

2/2 – Way directional control valve, normally open



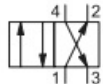
3/2 – Way directional control valve, normally closed



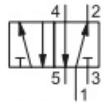
3/2 – Way directional control valve, normally open



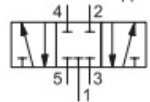
4/2 – Way directional control valve
Flow from 1 → 2 and from 4 → 3



5/2 – Way directional control valve
Flow from 1 → 2 and von 4 → 5

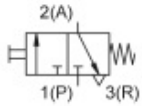


5/3 – Way directional control valve
Mid position closed

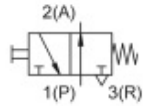


INPUT ELEMENT 1

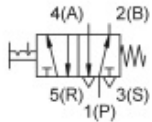
3/2-way valve with push button,
normally closed



3/2-way valve with push button,
normally open



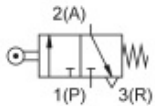
5/2-way valve with selector switch



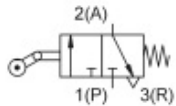
Pressure gauge



3/2-way roller lever valve,
normally closed



3/2-way roller lever valve with idle
return, normally closed



Pneumatic

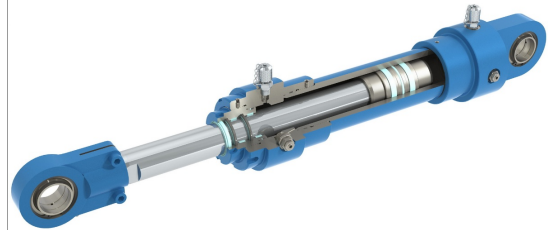
Electropneumatic

POWER COMPONENTEN

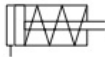
Actuators can be further broken down into groups:

- Linear actuators
 - Single-acting cylinder
 - Double-acting cylinder
- Rotary actuators
 - Air motors
 - Rotary actuators

Fig. 2.13
Actuators, linear and rotary



Single-acting cylinder



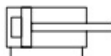
Double-acting cylinder



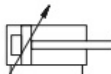
Double-acting cylinder
with double ended piston rod



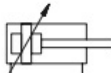
Double-acting cylinder
with non-adjustable cushioning
in one direction



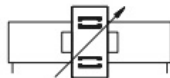
Double-acting cylinder
with single adjustable cushioning



Double-acting cylinder
with adjustable cushioning
at both ends



Linear drive with
magnetic coupling



Air motor, rotation in one direction
fixed capacity



Air motor, rotation in one direction
variable capacity



Air motor, rotation in both directions
variable capacity



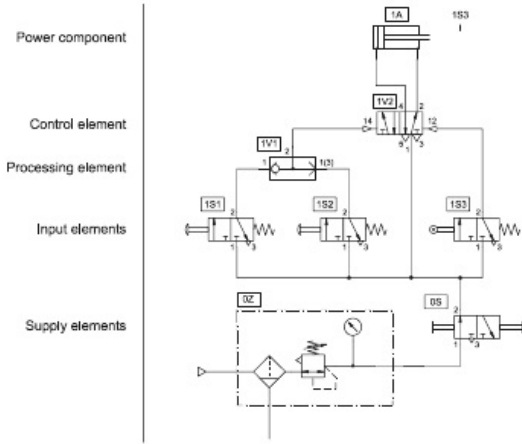
Rotary actuator



ctropneumatic

Pneumatic

BAGIAN BAGIAN DARI PNEUMATIC



Pneumatic

Fig. 5.5: Pneumatic circuit diagram of the lifting device

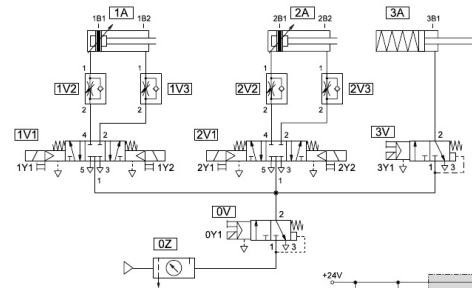


Fig. 4.3 Circuit diagram

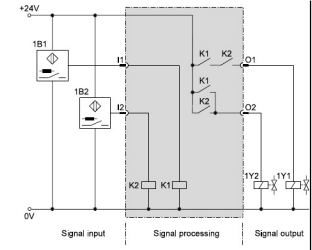
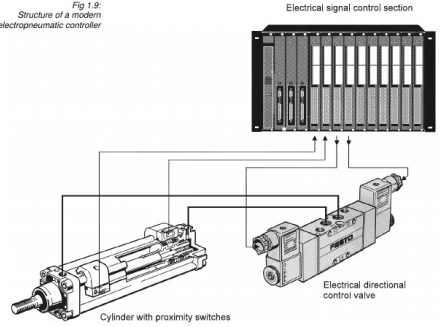


Fig. 3.20: Signal control section of relay control system (schematic, circuit diagram not compliant with standard)



Fig. 1.9: Structure of a modern electropneumatic controller

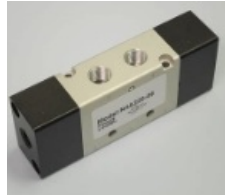
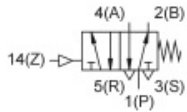


Electropneumatic

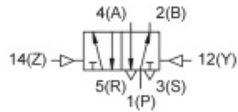
FINAL CONTROL ELEMENT



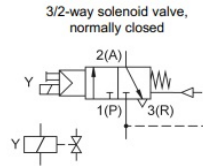
5/2-way pilot valve



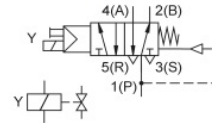
5/2-way double pilot valve



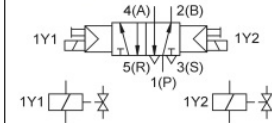
Pneumatic



5/2-way solenoid valve



5/2-way double solenoid valve

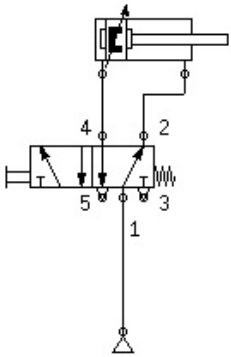


Indicator and distributor plate, electrical

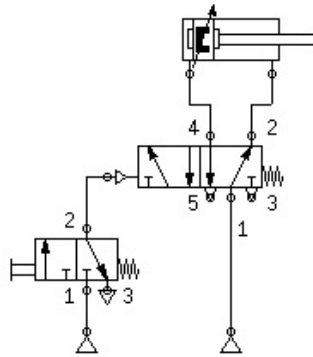


Electropneumatic

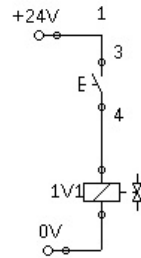
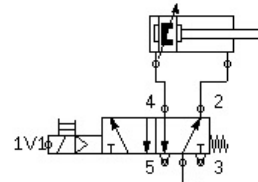
KENDALI SECARA LANGSUNG DAN TIDAK LANGSUNG



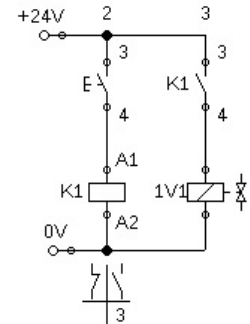
Langsung



Tidak Langsung



Langsung



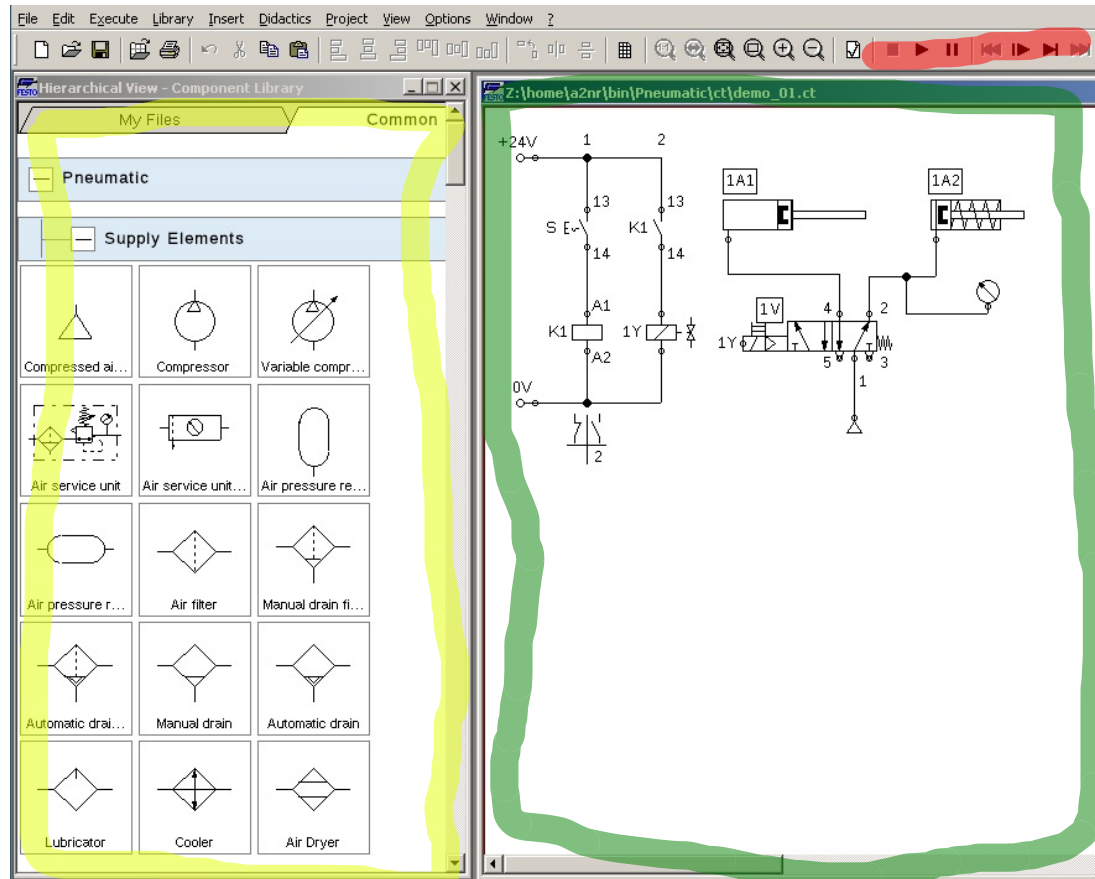
Tidak Langsung

Pneumatic

Electropneumatic

Mendesain Rangkaian Dengan FluidSim

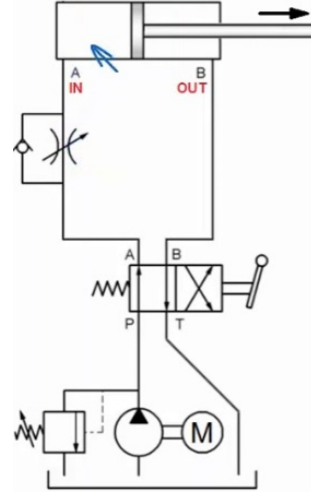
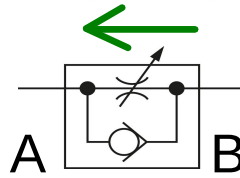
- *Untuk mencari komponen
- *untuk meletakkan komponen
- *untuk menjalankan simulasi



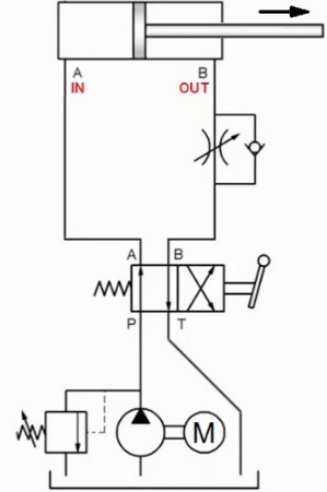
PRAKTIKUM 1

PROCESSING ELEMENT 1

One-way flow control valve

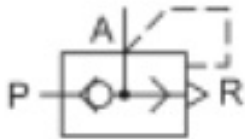


Meter-in for Extension
Uncontrolled for Retraction



Meter-out for Extension
Uncontrolled for Retraction

Quick exhaust valve

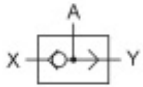


Pneumatic

PROCESSING ELEMENT 2

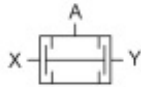
OR

Shuttle valve

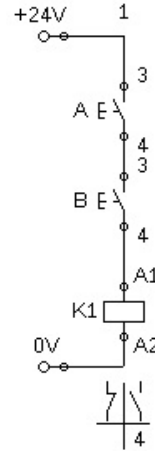


AND

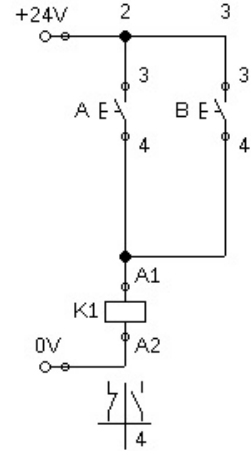
Dual-pressure valve



AND



OR



AND

A	B	$A \wedge B$
True	True	True
True	False	False
False	True	False
False	False	False

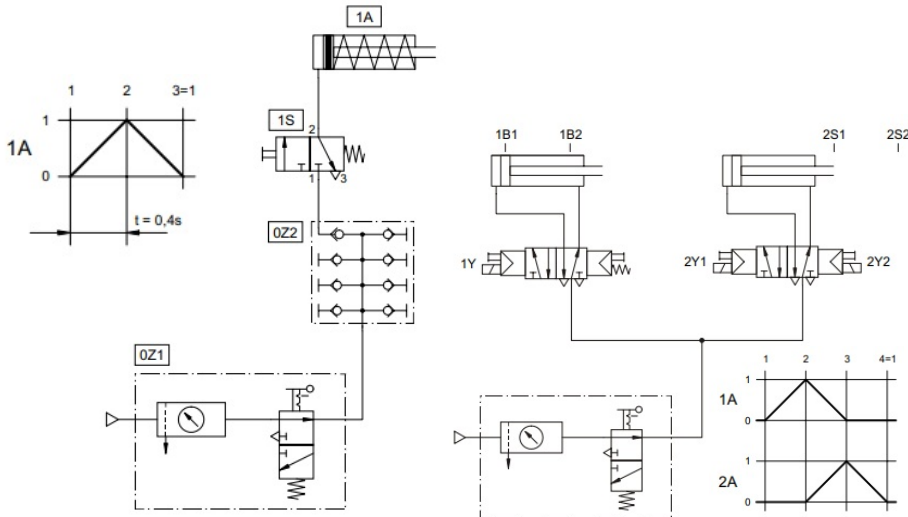
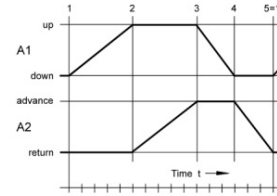
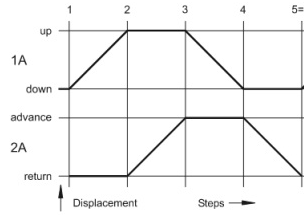
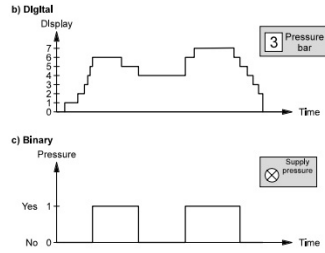
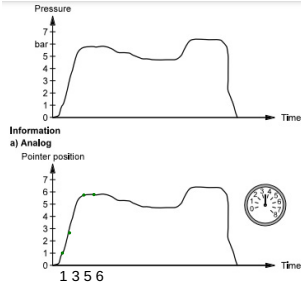
OR

A	B	$A \vee B$
True	True	True
True	False	True
False	True	True
False	False	False

Pneumatic

Electropneumatic

Grafik Pergerakan Pneumatic



PRAKTIKUM 2

PEMBERIAN LABEL KOMPONEN

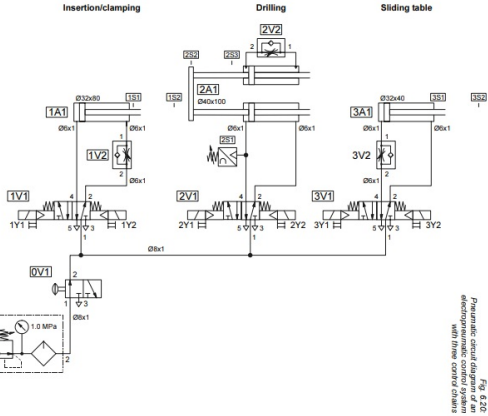
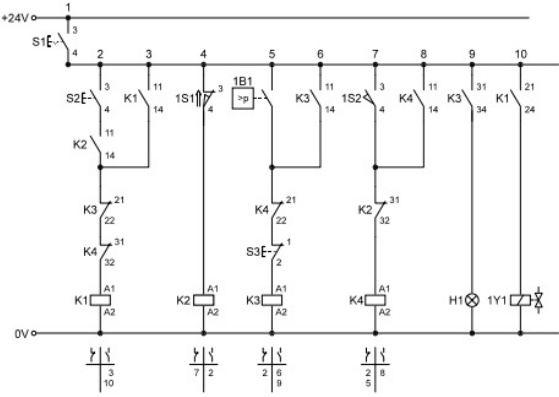


Fig. 6.28:
Electrical circuit diagram
of an electropneumatic
control system



S1 = Main switch
S2 = Start switch
S3 = Acknowledgement switch
1S1/1S2 = Limit switch
1B1 = Pressure switch

1 - 1 S 2

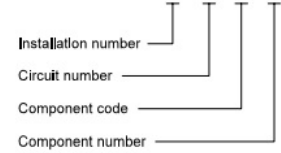


Fig. 6.21:
Identification code for
components in pneumatic
circuit diagrams

Table 6.3:
Identification codes for
components in a
pneumatic circuit diagram

Components	Identification
Compressors	P
Power components	A
Drive motors	M
Sensors	S
Valves	V
Valve coils	Y*
Other components	Z**

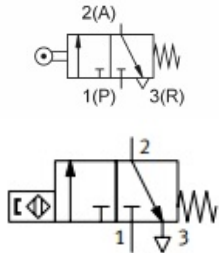
* national supplement in German standard
** or any other letter not included in the list

Component type	Identification
Limit switch	S
Manually operated pushbutton, input elements	S
Reed switch	B
Electronic proximity switch	B
Pressure switch	B
Indicator	H
Relay	K
Contactors	K
Solenoid coil of a valve	Y

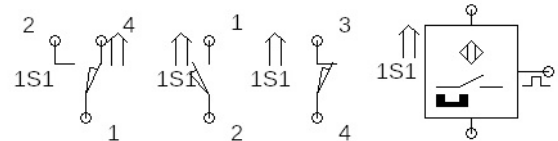
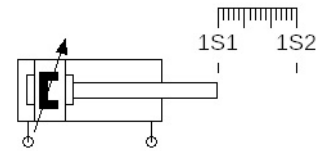
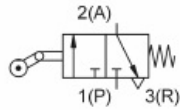
Table 6.4:
Designation of components
in an electrical circuit
diagram
(DIN 40719, Part 2)

INPUT ELEMENT 2

3/2-way roller lever valve,
normally closed



3/2-way roller lever valve with idle
return, normally closed



Limit switch, electrical,
Actuation from left or right*

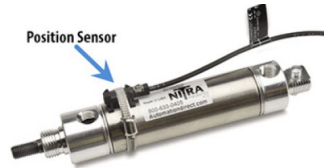
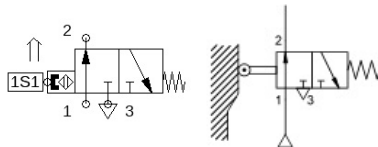


Fig. 4.6
Actuated initial position

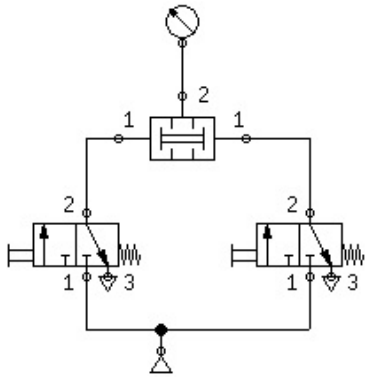


Pneumatic

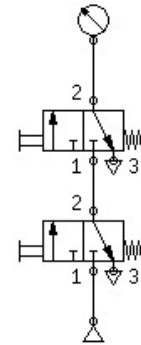
Electropneumatic

PROCESSING ELEMENT 3

Logika AND



Pneumatic



Electropneumatic

Grafik Pergerakan Pneumatic 2

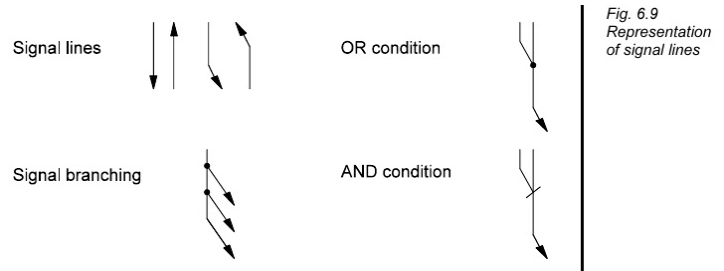
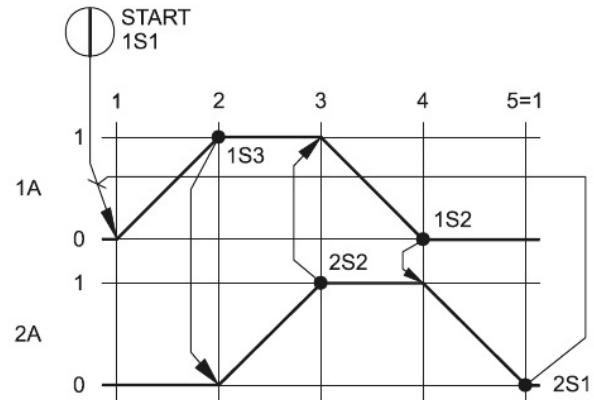
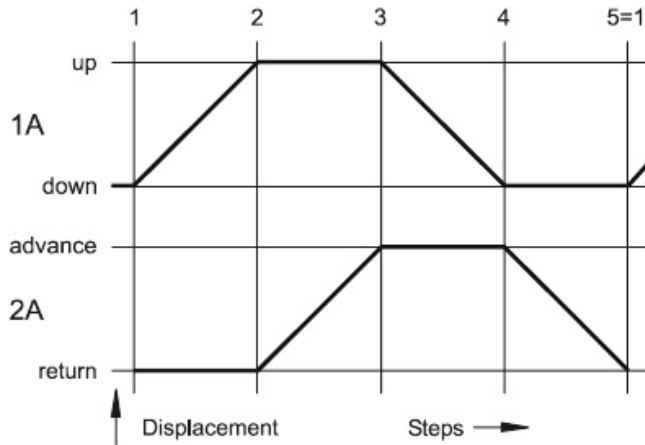
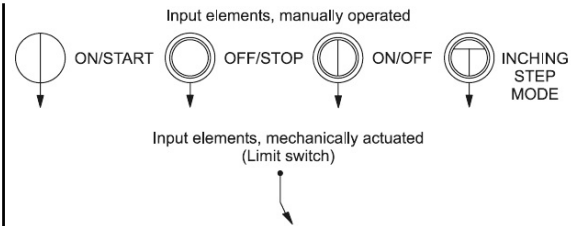


Fig. 6.9
Representation
of signal lines

Fig. 6.10
Representation
of input elements



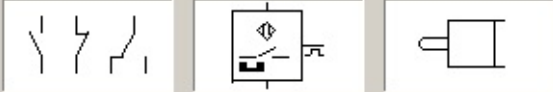
Cara memberikan label limit

Configure Cylinder

Configuration Parameters External load Force profile Actuating Labels

Label	Position		mm (0..100)
	Begin	End	
151	100	100	mm (0..100)
			mm (0..100)
			mm (0..100)
			mm (0..100)
			mm (0..100)
			mm (0..100)

Corresponding components



OK Cancel Help

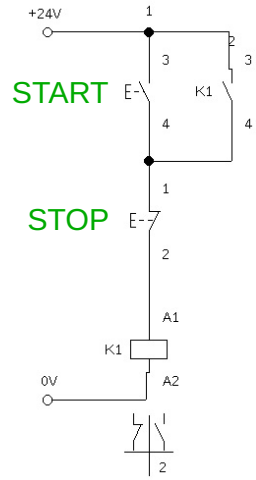
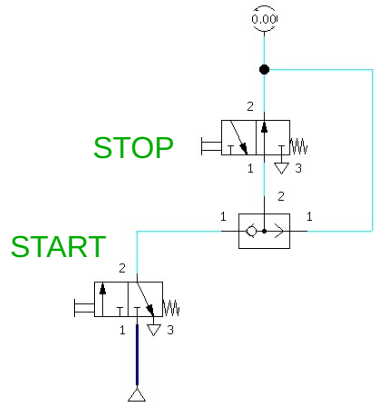
PRAKTIKUM 3

PROCESSING ELEMENT 3

Dominan-OFF

Ciri - Ciri

- Valve Start ditekan, angin/listrik keluar dari valve Stop
- Valve Start ditekan, valve stop ditekan, angin tidak keluar



Pneumatic

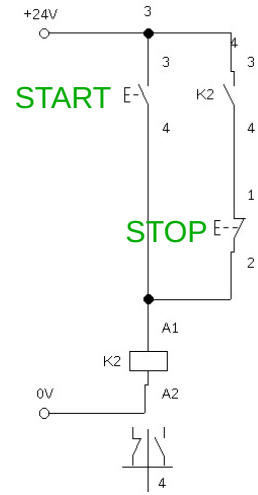
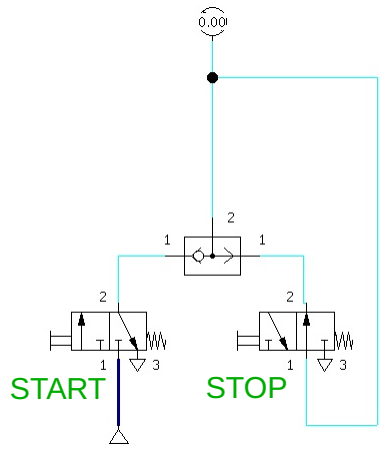
Electropneumatic

PROCESSING ELEMENT 3

Dominan-ON

Ciri - Ciri

- Valve Start ditekan, angin/listrik keluar dari valve Stop
- Valve Start ditekan, valve stop ditekan, angin keluar

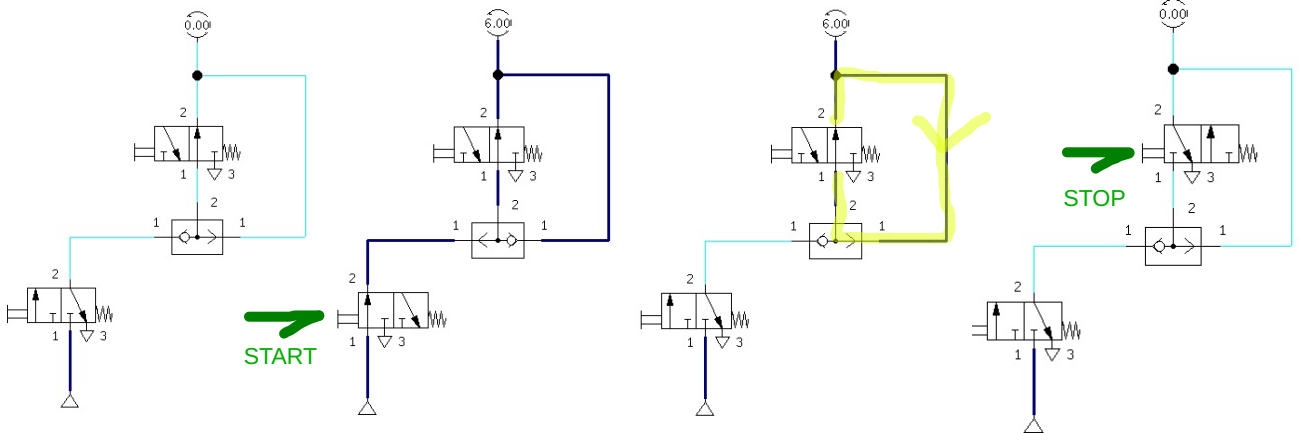


Pneumatic

Electro pneumatic

PROCESSING ELEMENT 3

Dominan-OFF

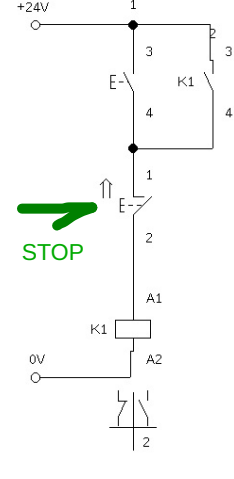
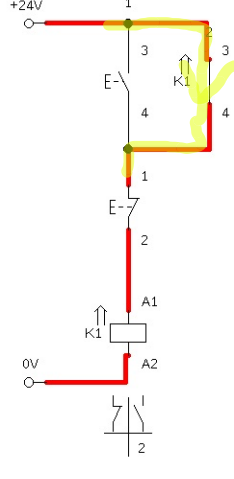
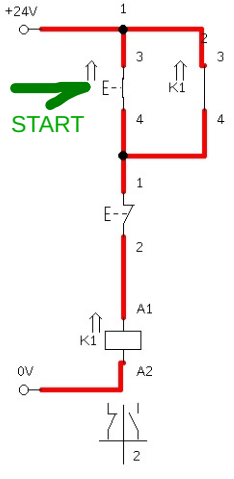
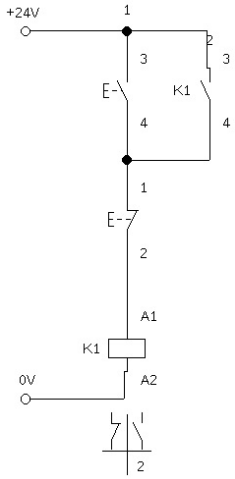


1

2

3

4

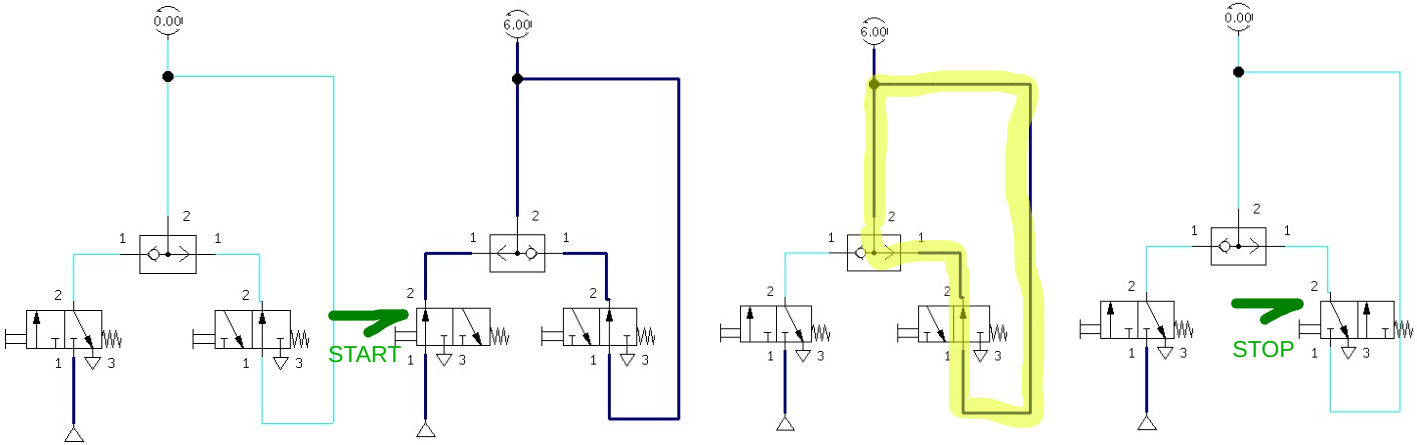


Pneumatic

Electronmagnetic

PROCESSING ELEMENT 3

Dominan-ON

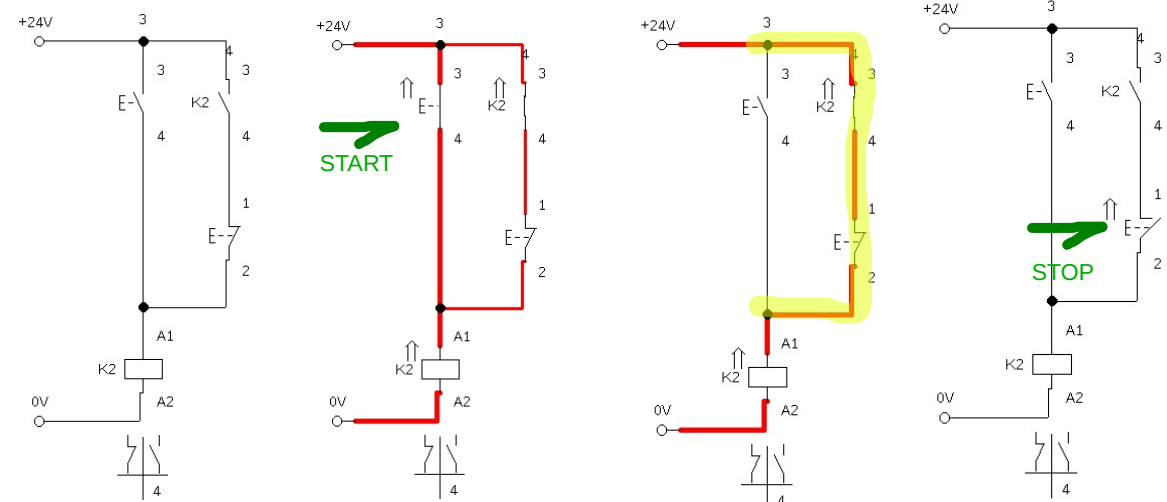


1

2

3

4

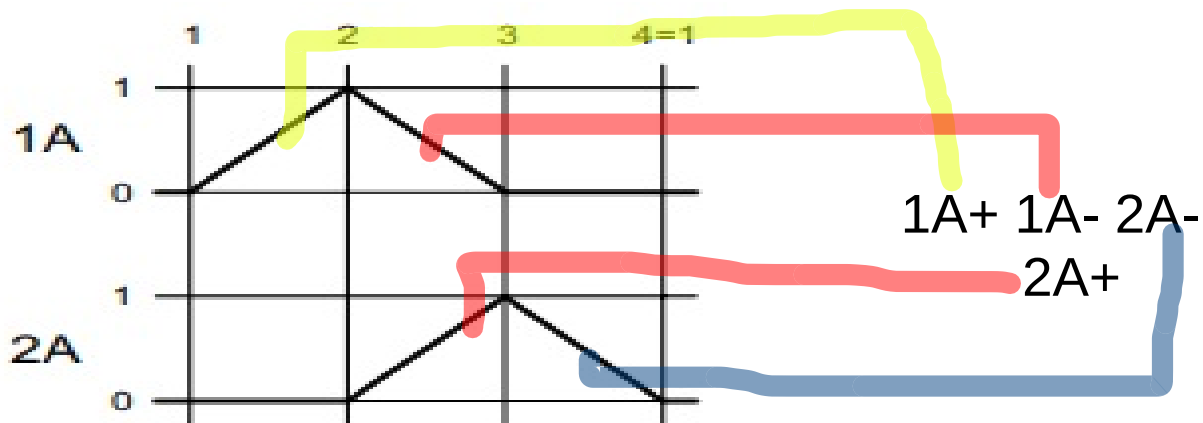
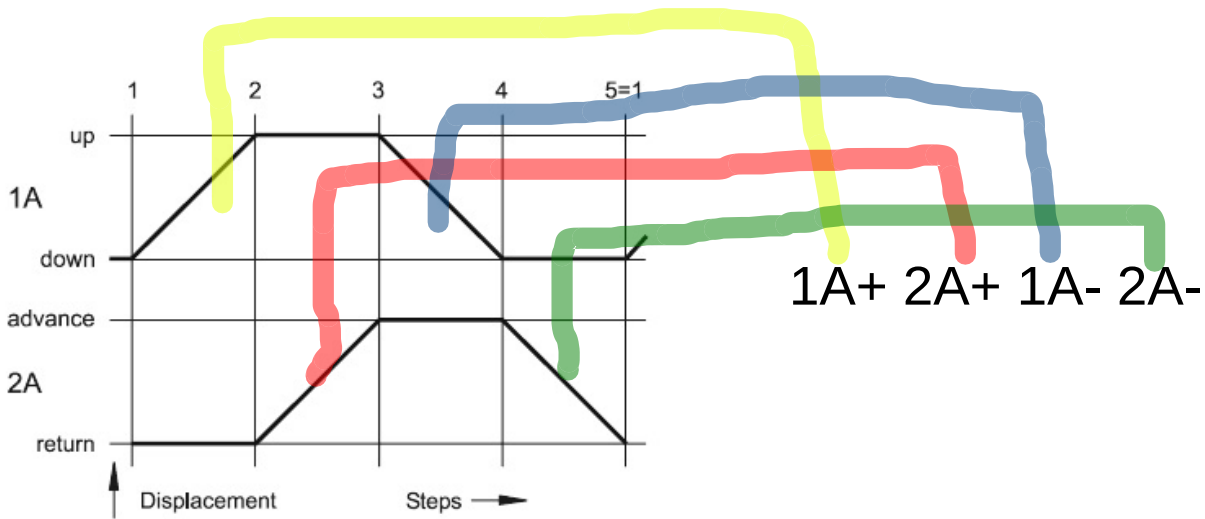


Pneumatic

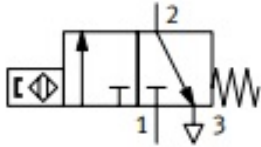
Electropneumatic

PRAKTIKUM 4

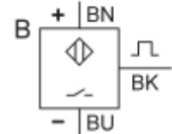
Grafik Pergerakan Pneumatic 3



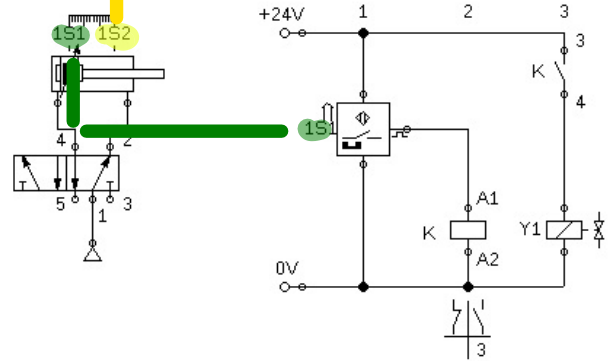
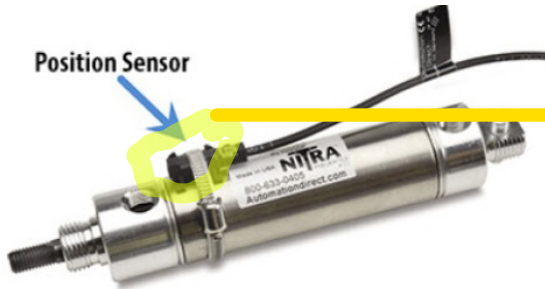
INPUT ELEMENT 3



Proximity sensor with cylinder mounting



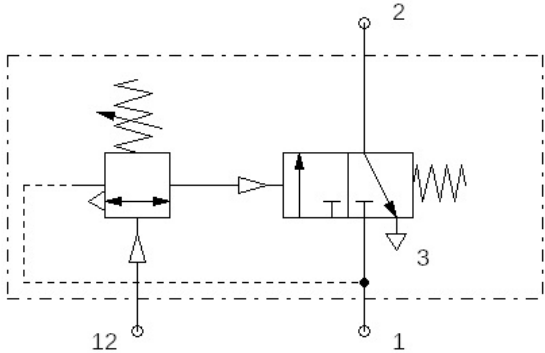
Position Sensor



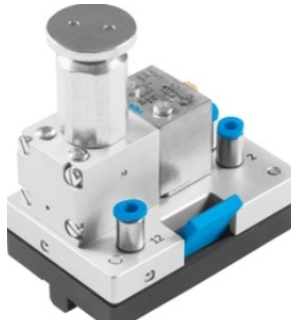
Pneumatic

Electronpneumatic

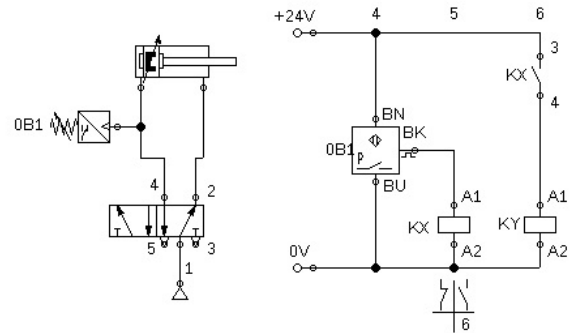
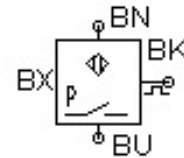
INPUT ELEMENT 3



Pressure Squance Valve



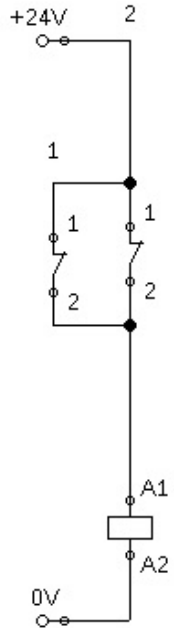
Pneumatic



Electronpneumatic

PROCESSING ELEMENT 3

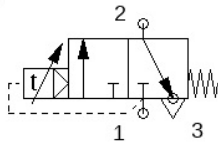
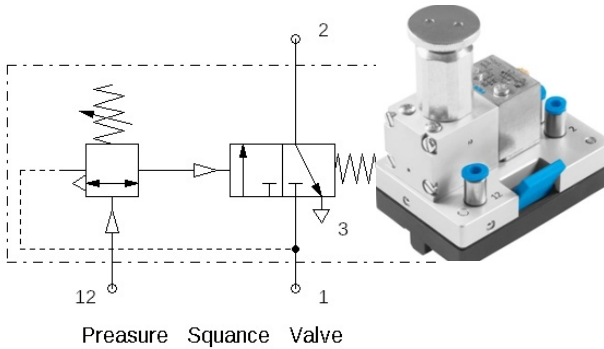
Logika NAND



Pneumatic

Electropneumatic

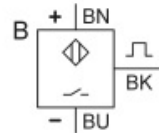
INPUT ELEMENT 3



Pneumatic Timer, Normally Close

Pneumatic

Proximity sensor with cylinder mounting



Position Sensor

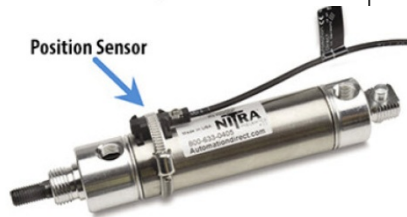
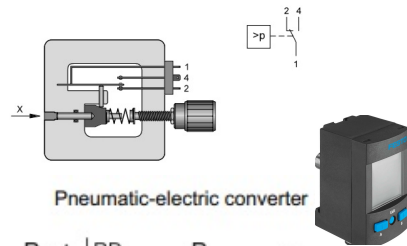
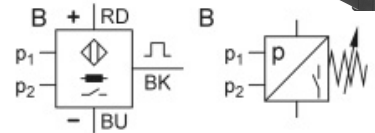


Fig. 3.12: Piston-actuated pressure switch



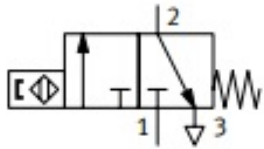
Pneumatic-electric converter



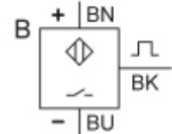
Electropneumatic

PRAKTIKUM 5

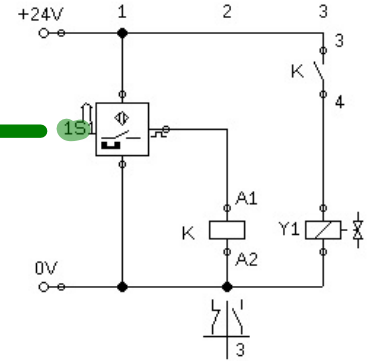
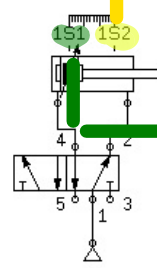
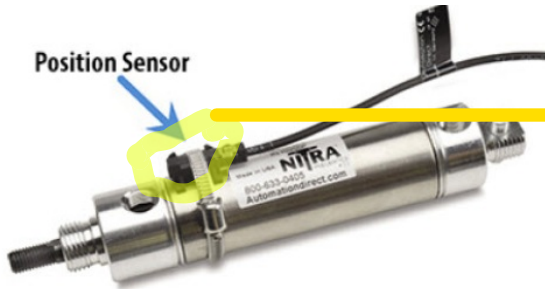
INPUT ELEMENT 3



Proximity sensor with cylinder mounting



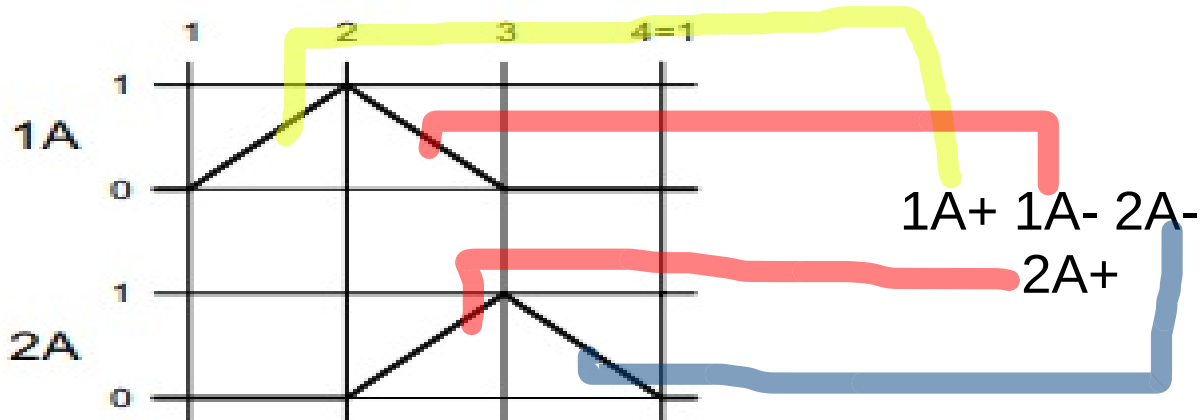
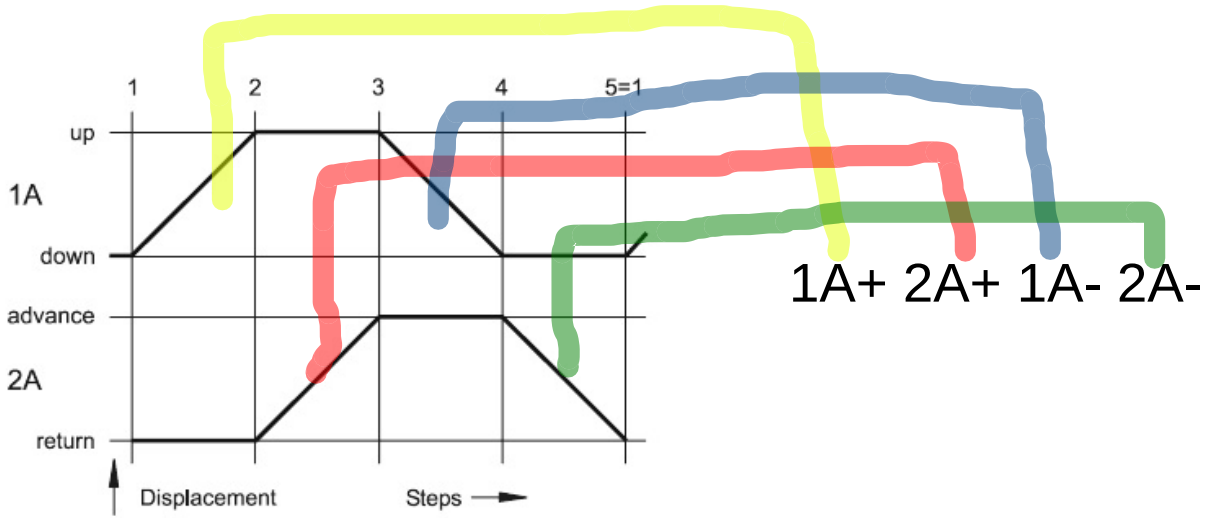
Position Sensor



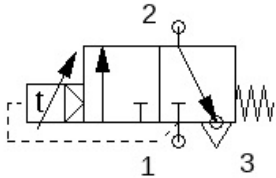
Pneumatic

Electronneumatic

Grafik Pergerakan Pneumatic 3

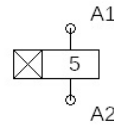


INPUT ELEMENT 3

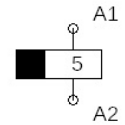
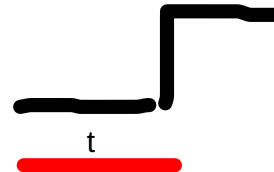


Pneumatic Timer, Normally Close

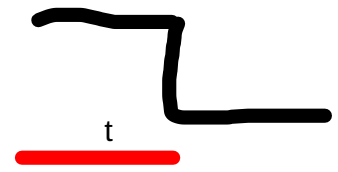
Pneumatic



Switch-On Delay

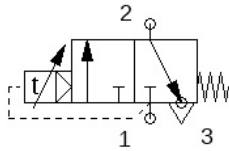


Switch-Off Delay

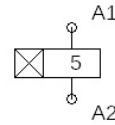


Electronneumatic

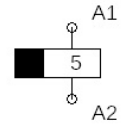
INPUT ELEMENT 3



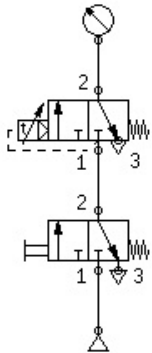
Pneumatic Timer, Normally Close



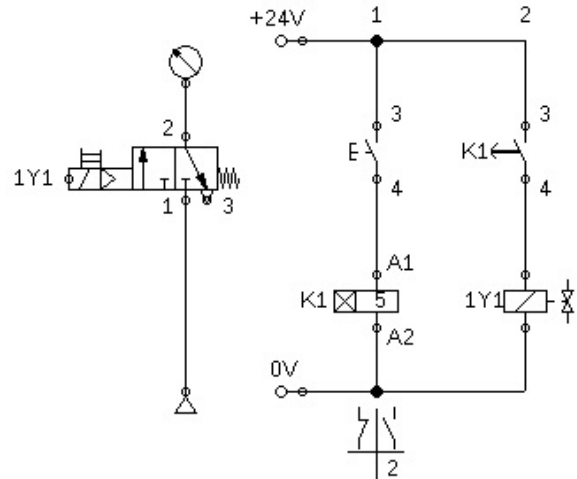
Switch-On Delay



Switch-Off Delay



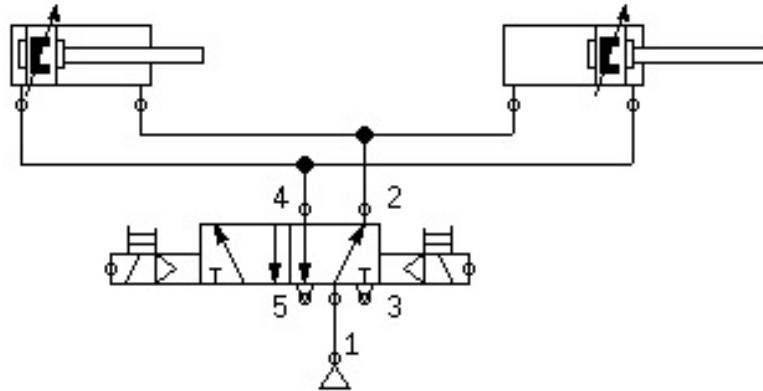
Pneumatic



Electronneumatic

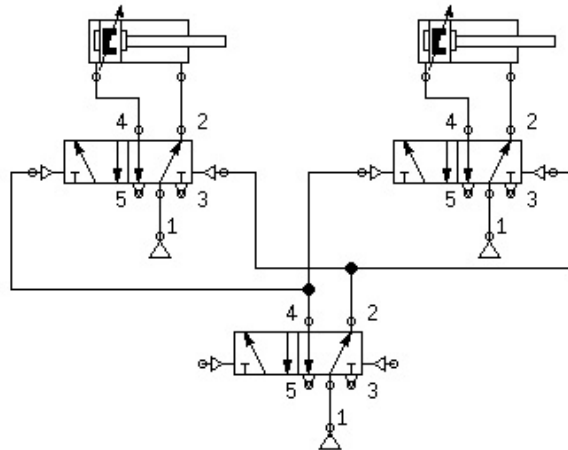
PRAKTIKUM 6

Mengendalikan Silinder Lebih Dari Satu secara langsung



- + Satu valve mengendalikan banyak aktuator
- + Satu aktuator mempresentasikan kondisi aktuator lain
- Kendali setiap aktuator terbatas
- Gaya dorong satu valve terbagi menjadi dua

Mengendalikan Silinder Lebih Dari Satu secara tidak langsung



- + Satu valve mengendalikan banyak aktuator
- + Banyak kombinasi gerak yang bisa dilakukan
- + Gaya dorong yang kuat dan sama
- Rangkaian menjadi kompleks
- Banyak membutuhkan komponen

PRAKTIKUM 7