

PELAJARAN HARI INI

1. Fisika Dasar dan Satuan yang berkaitan dengan Sistem Pneumatik
2. Urutan Perangkat Penyuplai Angin
3. Cara Kerja Katup Sistem Pneumatik

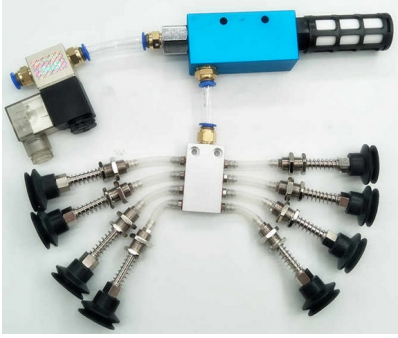
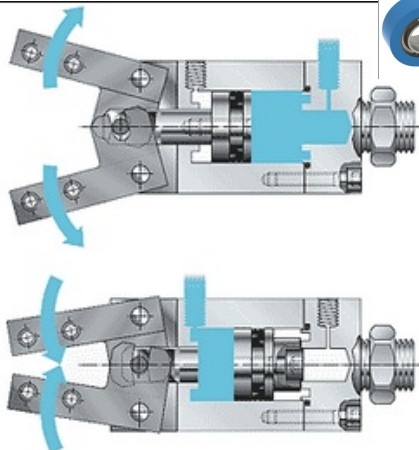
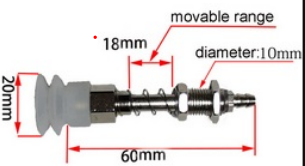
APA YANG DIKENDALIKAN DI SISTEM PNEUMATIC?

Actuators can be further broken down into groups:

- Linear actuators
 - Single-acting cylinder
 - Double-acting cylinder
- Rotary actuators
 - Air motors
 - Rotary actuators



Fig. 2.13 Actuators, linear and rotary



UNTUK APA AKTUATORNYA?

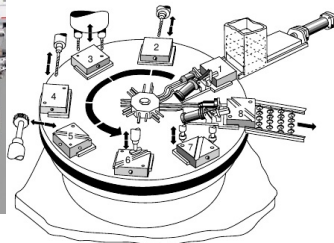
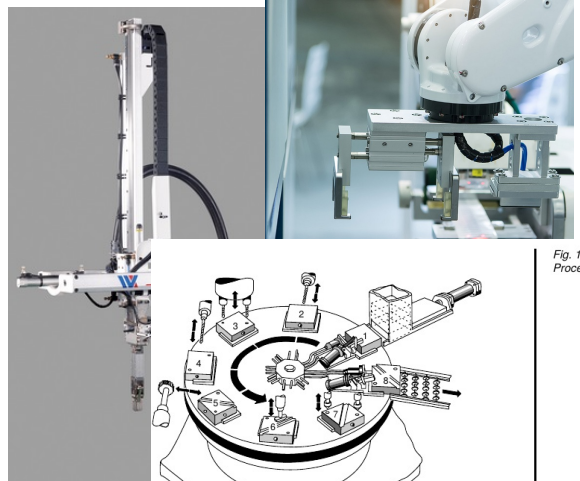


Fig. 1.2: Processing station

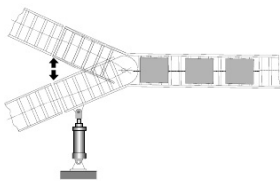


Fig. 1.2 Points switch for two conveyor belts



Fig. 1.3 Pneumatic cutter

Fig. 5.2 Positional sketch of the lifting device

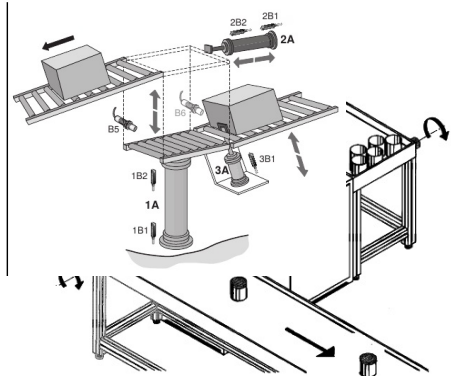


Fig. 1.3: Assembly device for mounting lids on cans

Pneumatic

Electropneumatic

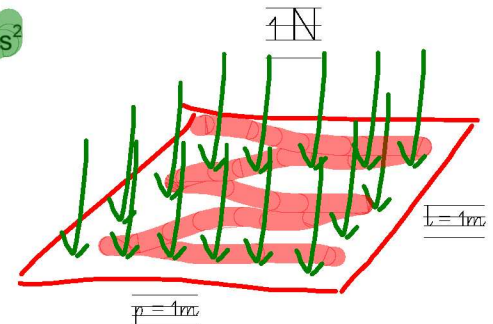
Mengenal Angin Bertekanan

Basic units	Quantity	Symbol	Units
<u>Panjang</u>	Length	L	Meter (m)
<u>Massa</u>	Mass	m	Kilogram (kg)
<u>Waktu</u>	Time	t	Second (s)
<u>Suhu</u>	Temperature	T	Kelvin (K, 0 °C = 273.15 K)

Hukum 2 Newton

$$F = m a$$

Derived units	Quantity	Symbol	Units
<u>Kepala</u>	Force	F	Newton (N) = 1 kg • m/s ²
<u>Luas</u>	Area	A	Square metre (m ²)
<u>Volume</u>	Volume	V	Cubic metre (m ³)
<u>Debit</u>	Flowrate	q _v	(m ³ /s)
<u>Tekanan</u>	Pressure	p	Pascal (Pa) 1 Pa = 1 N/m ² 1 bar = 10 ⁵ Pa



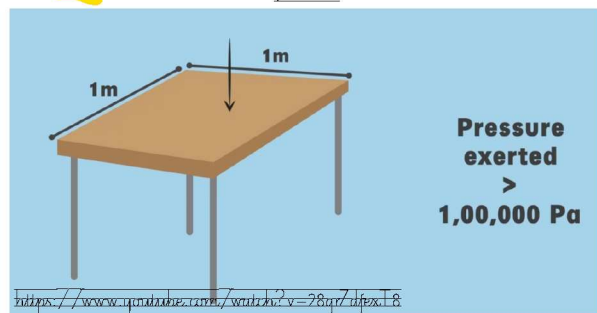
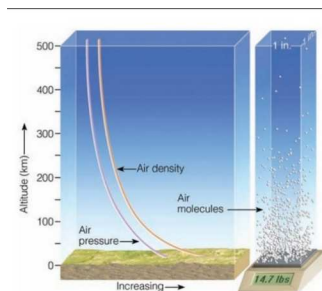
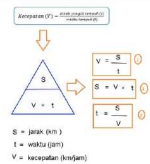
Rumus Percepatan:

$$a = \frac{v_1 - v_0}{t}$$

Keterangan:

- a = percepatan (m/s²)
- v₀ = kecepatan mula-mula (m/s)
- v₁ = kecepatan akhir (m/s)
- t = waktu (s)

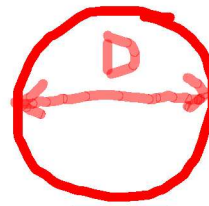
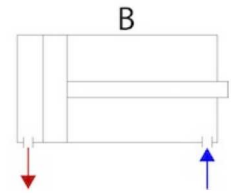
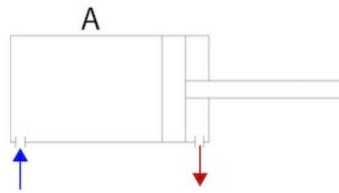
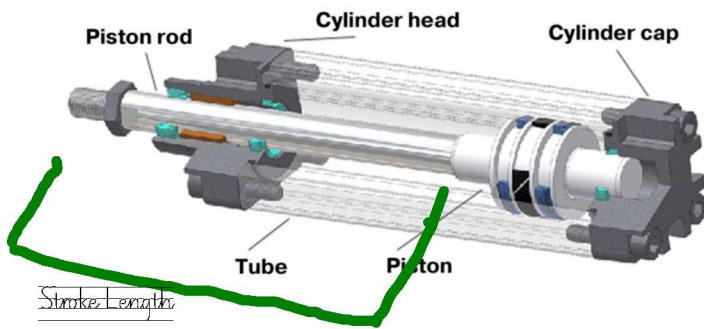
Akselerasi a m/s^2



Menentukan Silinder

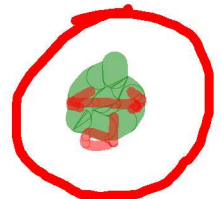
<https://www.studocu.com/pt/pages/pneumatic-cylinder-force-calculation>

Components of a piston rod cylinder:



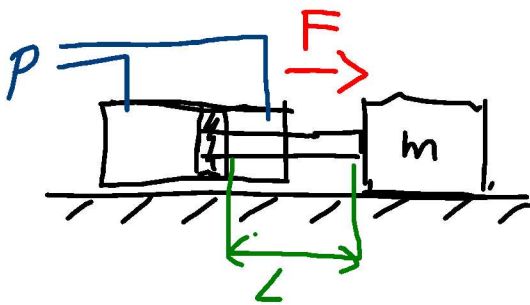
Piston Diameter
Diameter (Forward)

$$A = \frac{\pi}{4} \times D^2$$



Piston Diameter
Diameter (Retract)

$$A = \pi \times \frac{(D^2 - d^2)}{4}$$



$$F = m \cdot a$$

$$= m \cdot \frac{v_2 - v_1}{t} = 0$$

$$= m \cdot \frac{L}{t}$$

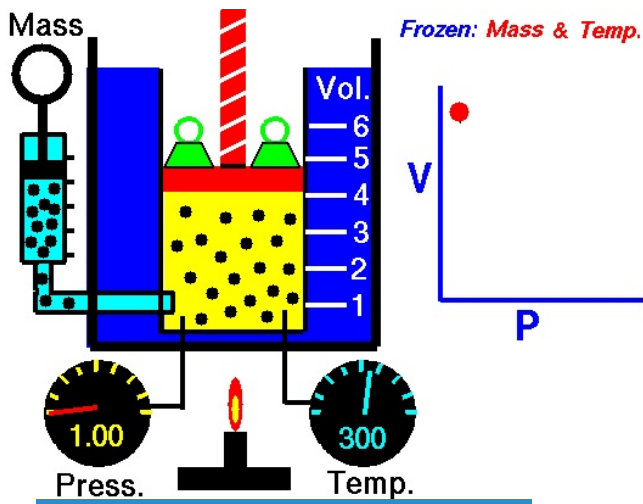
$$F = m \cdot \frac{L}{t^2}$$

$$P = \frac{F}{A}$$

$$\frac{\pi}{4} \times D^2 = \frac{F}{P}$$

$$D = \sqrt{\frac{F \cdot 4}{P \cdot \pi}}$$

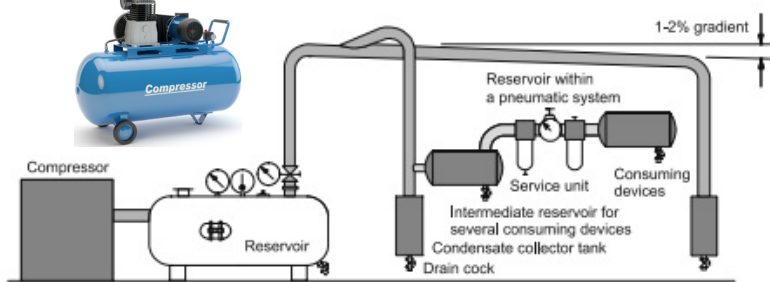
Karakteristik Angin



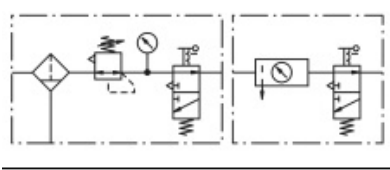
https://upload.wikimedia.org/wikipedia/commons/1/15/Boyles_Law_animated.gif



SUPLY ELEMENT



Service unit with on-off valve



Manifold

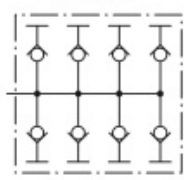
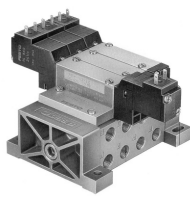


Fig. 4.12. Manifold of electrically actuated directional control valves on a valve manifold block (pneum)

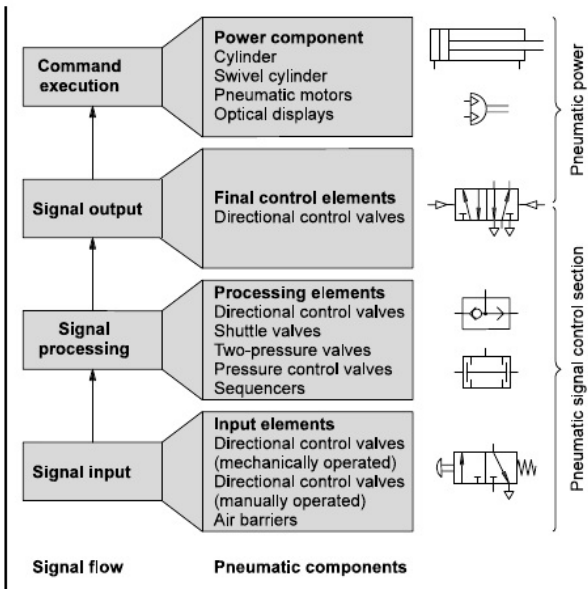


Pneumatic

Electropneumatic

BAGIAN BAGIAN DARI PNEUMATIC

Fig. 1.7: Signal flow and components of a pneumatic control system



Pneumatic

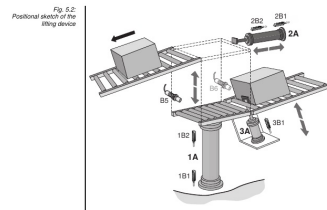
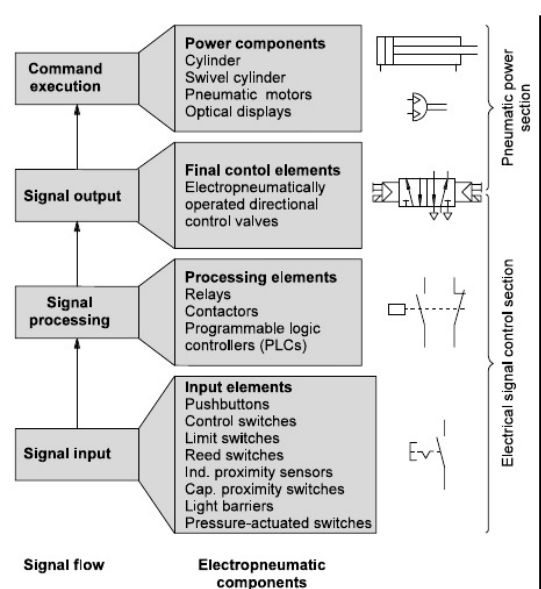
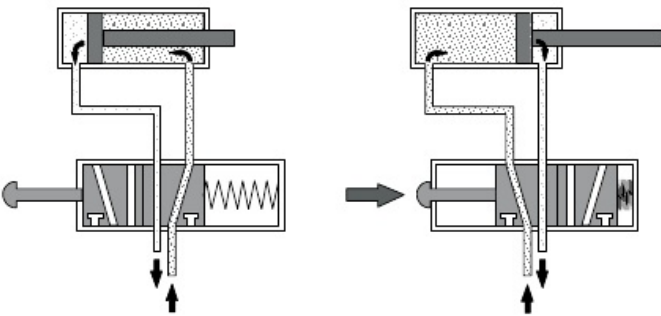


Fig. 1.8: Signal flow and components of an electropneumatic control system



Electropneumatic

BAGAIMANA MENGENDALIKAN AKTUATORNYA?



Pneumatic

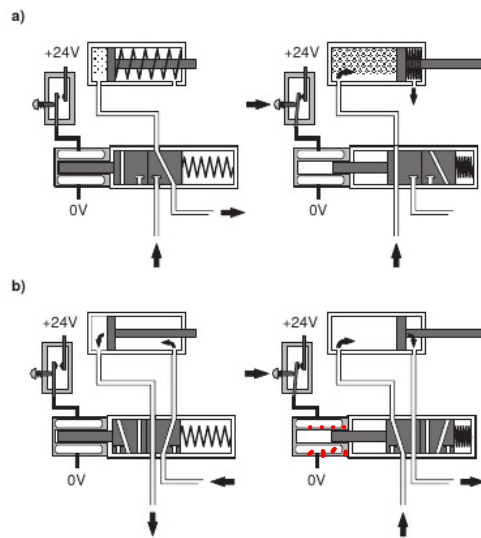
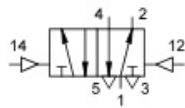
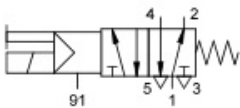
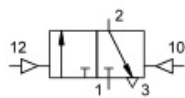
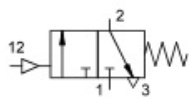


Fig. 4.1: Actuation of a pneumatic cylinder a) Single-acting b) Double-acting



Electropneumatic

MENGENAL VALVE 1



Valve switching positions are represented as squares



The number of squares shows how many switching positions the valve has



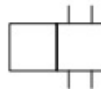
Lines indicate flow paths, arrows shows the direction of flow



Shut off positions are identified in the boxes by lines drawn at right angles



The connections (inlet and outlet ports) are shown by lines on the outside of the box

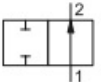


Working lines	ISO 5599-3	Lettering System	Port or Connection
	1	P	Pressure port
	2, 4	A, B	Working lines
	3, 5	R, S	Exhaust ports

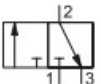
Pilot lines	ISO 5599-3	Lettering System	Port or Connection
	10	Z	Applied signal inhibits flow from port 1 to port 2
	12	Y, Z	Applied signal connects port 1 to port 2
	14	Z	Applied signal connects port 1 to port 4
	81, 91	Pz	Auxiliary pilot air

Number of ports
Number of positions

2/2 – Way directional control valve, normally open



3/2 – Way directional control valve, normally closed



3/2 – Way directional control valve, normally open



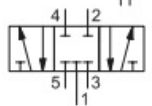
4/2 – Way directional control valve
Flow from 1 → 2 and from 4 → 3



5/2 – Way directional control valve
Flow from 1 → 2 and von 4 → 5

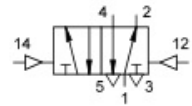
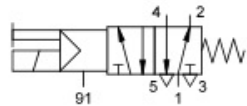
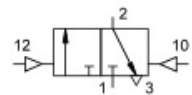
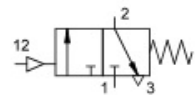


5/3 – Way directional control valve
Mid position closed



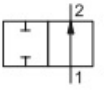
MENGENAL VALVE 2

Manual	General	
	Pushbutton	
	Lever Operated	
	Detend lever operated	
	Foot pedal	
Mechanical	Plunger	
	Roller operated	
	Idle return, roller	
	Spring return	
	Spring centred	
Pneumatic	Direct pneumatic actuation	
	Indirect pneumatic actuation (piloted)	
Electrical	Single solenoid operation	
	Double solenoid operation	
Combined	Double solenoid and pilot operation with manual override	

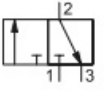


Number of ports
 Number of positions

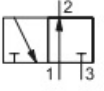
2/2 – Way directional control valve, normally open



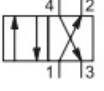
3/2 – Way directional control valve, normally closed



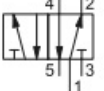
3/2 – Way directional control valve, normally open



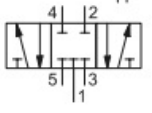
4/2 – Way directional control valve
Flow from 1 → 2 and from 4 → 3



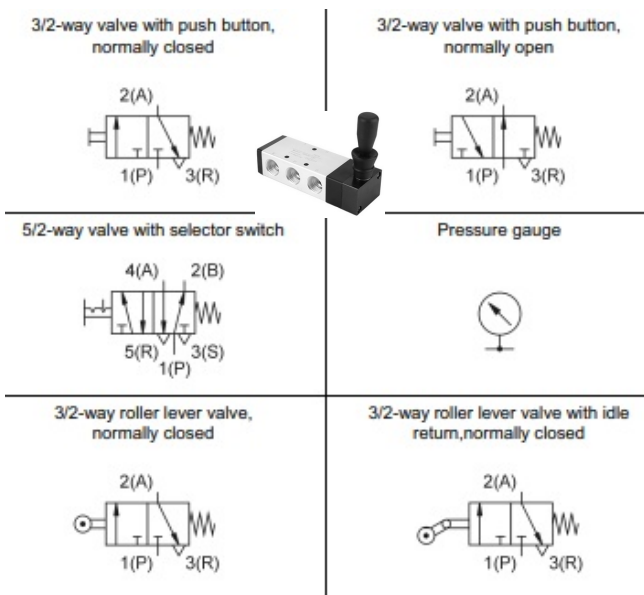
5/2 – Way directional control valve
Flow from 1 → 2 and von 4 → 5



5/3 – Way directional control valve
Mid position closed



INPUT ELEMENT 1



Pneumatic

Electropneumatic

POWER COMPONENTS

Actuators can be further broken down into groups:

- Linear actuators
 - Single-acting cylinder
 - Double-acting cylinder
- Rotary actuators
 - Air motors
 - Rotary actuators

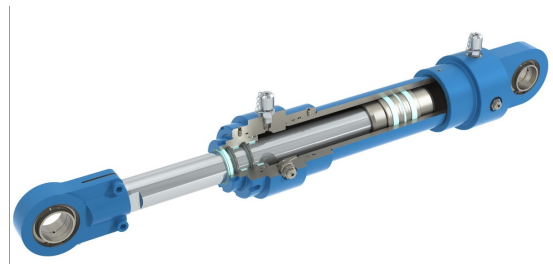
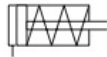


Fig. 2.13
Actuators, linear and rotary



Single-acting cylinder



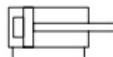
Double-acting cylinder



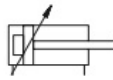
Double-acting cylinder with double ended piston rod



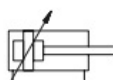
Double-acting cylinder with non-adjustable cushioning in one direction



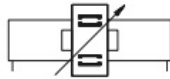
Double-acting cylinder with single adjustable cushioning



Double-acting cylinder with adjustable cushioning at both ends



Linear drive with magnetic coupling



Air motor, rotation in one direction fixed capacity



Air motor, rotation in one direction variable capacity



Air motor, rotation in both directions variable capacity



Rotary actuator



ctropneumatic
Pneumatic